

# Refracted-Reflected Spectrally one-sided Lévy Processes

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# Reflected & Refracted Lévy Processes

- Reflected Lévy processes:  $U_t := X_t - L_t$  where

$$L_t := \sup_{0 \leq t' \leq t} (X_{t'} - b) \vee 0, \quad t \geq 0.$$

- Refracted Lévy processes (Kyprianou and Loeffen, 2009)

- A strong Markov process given by the unique strong sol'n to the SDE

$$dA_t = dX_t - \delta \mathbf{1}_{\{A_t > b\}} dt, \quad t \geq 0.$$

- Namely,  $A$  progresses like  $X$  below the boundary  $b$  while it does like

$$Y_t := X_t - \delta t, \quad t \geq 0,$$

above  $b$ .

## Refracted-Reflected Lévy Processes

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- Refracted at an upper boundary  $b$ , and
- Reflected at a lower boundary  $0$ .

Step 0 Set  $V_{0-} = x$ . If  $x \geq 0$ , then set  $\underline{\tau} := 0$  and go to **Step 1**. Otherwise, set  $\bar{\tau} := 0$  and go to **Step 2**.

Step 1 Let  $\{\tilde{A}_t; t \geq \underline{\tau}\}$  be the refracted Lévy process (with refraction level  $b$ ) that starts at the time  $\underline{\tau}$  at the level  $x$ , and  $\bar{\tau} := \inf\{t > \underline{\tau} : \tilde{A}_t < 0\}$ . Set  $V_t = \tilde{A}_t$  for all  $\underline{\tau} \leq t < \bar{\tau}$ . Then go to **Step 2**.

Step 2 Let  $\{\tilde{U}_t; t \geq \bar{\tau}\}$  be the Lévy process reflected at the lower boundary  $0$  that starts at time  $\bar{\tau}$  at  $0$ , and  $\underline{\tau} := \inf\{t > \bar{\tau} : \tilde{U}_t > b\}$ . Set  $V_t = \tilde{U}_t$  for all  $\bar{\tau} \leq t < \underline{\tau}$ . Then go to **Step 1**.

## Decomposition

We have a decomposition:

$$V_t = X_t + R_t - L_t, \quad t \geq 0.$$

In particular, we have

$$L_t = \delta \int_0^t 1_{\{V_s > b\}} ds, \quad t \geq 0,$$

and for the case of bounded variation

$$R_t = \sum_{t \geq 0: V_{t-} + \Delta X_t < 0} |V_{t-} + \Delta X_t| \quad t \geq 0.$$

# Applications

- M/G/1 queues with abandonments
  - (reflection) The length of queues does not go negative.
  - (refraction) When the queue is long, some people may decide not to line up.
- Optimal dividends with capital injection
  - (reflection) Pay dividends at a constant rate  $\delta$  when it is above  $b$ .
  - (refraction) Must inject capital to prevent it from going below zero.
- Optimal dividends with both singular and absolutely continuous control
  - (reflection) Pay dividends at a constant rate  $\delta$  when it is above  $a$ .
  - (refraction) Pay dividends so that it does not go above  $b(> 0)$ .

## Objective

We compute fluctuation identities – with  $T_a^+ := \inf\{t > 0 : V_t > a\}$ ,

- Resolvents:

$$\mathbb{E}_x \left( \int_0^{T_a^+} e^{-qt} 1_{\{V_t \in B\}} dt \right)$$

- expected NPVs (net present value) of total discounted  $L$  and  $R$ :

$$\mathbb{E}_x \left( \int_0^{T_a^+} e^{-qt} dL_t \right) \quad \text{and} \quad \mathbb{E}_x \left( \int_{[0, T_a^+]} e^{-qt} dR_t \right).$$

- Laplace transform of occupation time:

$$\mathbb{E}_x \left( e^{-\rho T_a^+ - q \int_0^{T_a^+} 1_{\{V_s < b\}} ds} \right) \quad \text{and} \quad \mathbb{E}_x \left( e^{-\rho T_a^+ - q \int_0^{T_a^+} 1_{\{V_s > b\}} ds} \right).$$

## Usual Tricks

Define

- The drift-changed process  $Y_t := X_t - \delta t$ .
- The reflected process  $U$ :  $X$  reflected at lower level 0.

Almost surely, under  $\mathbb{P}_x$  for any  $x \in \mathbb{R}$ , we have

- $V_t = U_t$  on  $0 \leq t \leq T_b^+$ ,
- $V_t = Y_t$  on  $0 \leq t < T_b^-$  and  $V_{T_b^-} + \Delta X_{T_b^-} = Y_{T_b^-}$ .

In view of this, we use the fluctuation theory written in terms of the scale function of  $Y$  and  $U$  together with the strong Markov property of  $V$ .

# SN Lévy Processes and Laplace Exponents

- Given a SN Lévy process  $X = \{X_t; t \geq 0\}$ , the Laplace exponent is

$$\begin{aligned}\psi(\theta) := \log \mathbb{E}[e^{\theta X_1}] &= \gamma\theta + \frac{\sigma^2}{2}\theta^2 \\ &+ \int_{(-\infty, 0)} (e^{\theta z} - 1 - \theta z \mathbf{1}_{\{z > -1\}}) \Pi(dz), \quad \theta \geq 0.\end{aligned}$$

- $\Pi$  is a Lévy measure such that  $\int_{(-\infty, 0)} (1 \wedge z^2) \Pi(dz) < \infty$ .
- It has paths of bounded variation if and only if  $\sigma = 0$  and  $\int_{(-1, 0)} |z| \Pi(dz) < \infty$ .
- For the case of bounded variation, we can write

$$\psi(\theta) = \tilde{\gamma}\theta + \int_{(-\infty, 0)} (e^{\theta z} - 1) \Pi(dz), \quad \theta \geq 0,$$

with  $\tilde{\gamma} := \gamma - \int_{(-1, 0)} z \Pi(dz)$ .



## Scale Functions

- We use  $W^{(q)}$  and  $\mathbb{W}^{(q)}$  for the scale functions of  $X$  and  $Y$ , respectively. Namely, these are defined by

$$\int_0^{\infty} e^{-\theta x} W^{(q)}(x) dx = \frac{1}{\psi(\theta) - q}, \quad \theta > \Phi(q),$$

$$\int_0^{\infty} e^{-\theta x} \mathbb{W}^{(q)}(x) dx = \frac{1}{\psi(\theta) - \delta\theta - q}, \quad \theta > \varphi(q),$$

where

$$\Phi(q) := \sup\{\lambda \geq 0 : \psi(\lambda) = q\},$$

$$\varphi(q) := \sup\{\lambda \geq 0 : \psi(\lambda) - \delta\lambda = q\}.$$

# Fluctuations of Lévy Processes

- Let us define

$$\tau_a^- := \inf \{t > 0 : Y_t < a\} \quad \text{and} \quad \tau_a^+ := \inf \{t > 0 : Y_t > a\}.$$

- Then, for any  $a > b$  and  $x \leq a$ ,

$$\mathbb{E}_x \left( e^{-q\tau_a^+} \mathbf{1}_{\{\tau_a^+ < \tau_b^-\}} \right) = \frac{\mathbb{W}^{(q)}(x - b)}{\mathbb{W}^{(q)}(a - b)},$$

$$\mathbb{E}_x \left( e^{-q\tau_b^-} \mathbf{1}_{\{\tau_a^+ > \tau_b^-\}} \right) = \mathbb{Z}^{(q)}(x - b) - \mathbb{Z}^{(q)}(a - b) \frac{\mathbb{W}^{(q)}(x - b)}{\mathbb{W}^{(q)}(a - b)},$$

where

$$\overline{\mathbb{W}}^{(q)}(x) := \int_0^x \mathbb{W}^{(q)}(y) dy,$$

$$\mathbb{Z}^{(q)}(x) := 1 + q \overline{\mathbb{W}}^{(q)}(x).$$

## Resolvents and Overshoot

- The  $q$ -resolvent measure is

$$\mathbb{E}_x \left( \int_0^{\tau_b^- \wedge \tau_a^+} e^{-qt} \mathbf{1}_{\{Y_t \in dy\}} dt \right) = \left[ \frac{\mathbb{W}^{(q)}(x-b)\mathbb{W}^{(q)}(a-y)}{\mathbb{W}^{(q)}(a-b)} - \mathbb{W}^{(q)}(x-y) \right] dy.$$

- It is known that a spectrally negative Lévy process creeps downwards (i.e.  $\mathbb{P}_x(Y_{\tau_b^-} = b, \tau_b^- < \infty) > 0$  for  $x > b$ ) iff  $\sigma > 0$ .
- Hence, for the case of bounded variation,

$$\begin{aligned} & \mathbb{E}_x \left( e^{-q\tau_b^-} l(Y_{\tau_b^-}) \mathbf{1}_{\{\tau_b^- < \tau_a^+\}} \right) \\ &= \int_0^{a-b} \int_{(-\infty, -y)} l(y+u+b) \\ & \left\{ \frac{\mathbb{W}^{(q)}(x-b)\mathbb{W}^{(q)}(a-b-y)}{\mathbb{W}^{(q)}(a-b)} - \mathbb{W}^{(q)}(x-b-y) \right\} \Pi(du)dy. \end{aligned}$$

## Fluctuation of Reflected Processes

- Let  $\kappa_b^+ := \inf\{t > 0 : U_t > b\}$ .
- Its resolvent is

$$\mathbb{E}_x \left( \int_0^{\kappa_b^+} e^{-qt} 1_{\{U_t \in B\}} dt \right) = \frac{Z^{(q)}(x)}{Z^{(q)}(b)} \int_0^b W^{(q)}(b-y) 1_{\{y \in B\}} dy \\ - \int_0^x W^{(q)}(x-y) 1_{\{y \in B\}} dy.$$

- In particular,  $\mathbb{E}_x(e^{-q\kappa_b^+}) = Z^{(q)}(x)/Z^{(q)}(b)$ .
- If  $\tilde{R}_t := \sup_{s \leq t} (-X_s) \vee 0$  so that  $U_t = X_t + \tilde{R}_t$ ,

$$\mathbb{E}_x \left( \int_{[0, \kappa_b^+]} e^{-qt} d\tilde{R}_t \right) = - \left( \bar{Z}^{(q)}(x) + \frac{\psi'(0+)}{q} \right) \\ + \left( \bar{Z}^{(q)}(b) + \frac{\psi'(0+)}{q} \right) \frac{Z^{(q)}(x)}{Z^{(q)}(b)}.$$

## Resolvents

For  $q \geq 0$ ,  $x \leq a$  and a Borel set  $B$  on  $[0, a]$ ,

$$\mathbb{E}_x \left( \int_0^{T_a^+} e^{-qt} 1_{\{V_t \in B\}} dt \right) = \int_B \left( w^{(q)}(a, z) \frac{r^{(q)}(x)}{r^{(q)}(a)} - w^{(q)}(x, z) \right) dz,$$

where

$$\begin{aligned} r^{(q)}(x) &:= Z^{(q)}(x) + q\delta \int_b^x \mathbb{W}^{(q)}(x-y) W^{(q)}(y) dy, \\ w^{(q)}(x, z) &:= 1_{\{0 < z < b\}} \left( W^{(q)}(x-z) \right. \\ &\quad \left. + \delta \int_b^x \mathbb{W}^{(q)}(x-y) W^{(q)'}(y-z) dy \right) \\ &\quad + 1_{\{b < z < a\}} \mathbb{W}^{(q)}(x-z). \end{aligned}$$

## Sketch of Proof 1 (Bounded Var. Case)

For  $x < b$ , using the strong Markov property and because  $T_b^+ = \kappa_b^+$  (hitting time of  $U$ ) and  $V_t = U_t$ ,

$$\begin{aligned} f^{(q)}(x, a; B) &= \mathbb{E}_x \left( \int_0^{\kappa_b^+} e^{-qt} 1_{\{U_t \in B\}} dt \right) + \mathbb{E}_x (e^{-q\kappa_b^+}) f^{(q)}(b, a; B) \\ &= \frac{Z^{(q)}(x)}{Z^{(q)}(b)} \left[ \int_0^b W^{(q)}(b-y) 1_{\{y \in B\}} dy + f^{(q)}(b, a; B) \right] \\ &\quad - \int_0^x W^{(q)}(x-y) 1_{\{y \in B\}} dy. \end{aligned}$$

## Sketch of Proof 2 (Bounded Var. Case)

For  $x \geq b$  because  $T_b^- = \tau_b^-$  (hitting time of  $Y$ ) and  $V_t = Y_t$  on  $0 \leq t < T_b^-$  and  $V_{T_b^-} + \Delta X_{T_b^-} = Y_{\tau_b^-}$ ,

$$\begin{aligned} f^{(q)}(x, a; B) &= \mathbb{E}_x \left( \int_0^{\tau_a^+ \wedge \tau_b^-} e^{-qt} 1_{\{Y_t \in B\}} dt \right) \\ &+ \mathbb{E}_x \left( e^{-q\tau_b^-} f^{(q)}(Y_{\tau_b^-}, a; B) 1_{\{\tau_b^- < \tau_a^+\}} \right) \\ &= \int_b^a 1_{\{y \in B\}} \left\{ \frac{\mathbb{W}^{(q)}(x-b)\mathbb{W}^{(q)}(a-y)}{\mathbb{W}^{(q)}(a-b)} - \mathbb{W}^{(q)}(x-y) \right\} dy \\ &+ \int_0^{a-b} \int_{(-\infty, -y)} f^{(q)}(y+u+b, a; B) \\ &\times \left\{ \frac{\mathbb{W}^{(q)}(x-b)\mathbb{W}^{(q)}(a-b-y)}{\mathbb{W}^{(q)}(a-b)} - \mathbb{W}^{(q)}(x-b-y) \right\} \Pi(du) dy. \end{aligned}$$

## Sketch of Proof 3 (Bounded Var. Case)

Solving for  $f^{(q)}(b, a; B)$  (+ using some simplification formula), we obtain

$$f^{(q)}(b, a; B) = Z^{(q)}(b) \frac{\int_B w^{(q)}(a, z) dz}{r^{(q)}(a)} - \int_0^b W^{(q)}(b-y) 1_{\{y \in B\}} dy.$$

Plugging this back in the previous relations, we obtain  $f^{(q)}(x, a; B)$  for all  $x \geq 0$ .



## Extension to Unbounded Var. Case

1. Given a stochastic process  $(\xi_s; s \geq 0)$ , a sequence of processes  $\{(\xi_s^{(n)})_{s \geq 0}; n \geq 1\}$  is strongly approximating for  $\xi$ , if  $\lim_{n \uparrow \infty} \sup_{0 \leq s \leq t} |\xi_s - \xi_s^{(n)}| = 0$  for any  $t > 0$  a.s.
2. For any  $X$  of unbounded variation, we can construct a strongly approximating sequence  $X^{(n)}$  of bounded variation. The corresponding refracted-reflected processes  $V^{(n)}$  are strongly approximating for  $V$ .
3. The corresponding scale functions  $W_n^{(q)}$  and  $\mathbb{W}_n^{(q)}$  converge to  $W^{(q)}$  and  $\mathbb{W}^{(q)}$ .
  - Alternative proof – via excursion theory.

## Resolvents (Cont'd)

(i) For  $q > 0$ ,

$$\begin{aligned} & \mathbb{E}_x \left( \int_0^\infty e^{-qt} 1_{\{V_t \in B\}} dt \right) \\ &= \int_B \left( \frac{e^{-\varphi(q)z} 1_{\{b < z\}} + \delta 1_{\{0 < z < b\}} \int_b^\infty e^{-\varphi(q)u} W^{(q)'}(u-z) du}{\delta q \int_b^\infty e^{-\varphi(q)y} W^{(q)}(y) dy} r^{(q)}(x) \right. \\ & \left. - w^{(q)}(x, z) \right) dz. \end{aligned}$$

(ii) For  $q = 0$  and  $\psi_Y'(0+) > 0$  (or  $Y_t \xrightarrow{t \uparrow \infty} \infty$  a.s.), then

$$\begin{aligned} & \mathbb{E}_x \left( \int_0^\infty 1_{\{V_t \in B\}} dt \right) \\ &= \int_B \left( \frac{1_{\{b < z\}} + 1_{\{0 < z < b\}} (1 - \delta^{-1} W(b-z))}{\psi_Y'(0+)} - w^{(0)}(x, z) \right) dz. \end{aligned}$$

For  $q = 0$  and  $\psi_Y'(0+) \leq 0$ , it becomes infinity given  $\text{Leb}(B) > 0$ .

## Application of Resolvents

For any  $q \geq 0$  and  $x \leq a$ , we have

$$\mathbb{E}_x \left( e^{-qT_a^+} \right) = \frac{r^{(q)}(x)}{r^{(q)}(a)}.$$

In particular,  $T_a^+ < \infty$   $\mathbb{P}_x$ -a.s.

## Application of Resolvents (Cont'd)

Recall

$$L_t = \delta \int_0^t 1_{\{V_s > b\}} ds, \quad t \geq 0.$$

- For any  $q \geq 0$ ,  $x \leq a$  we have

$$\mathbb{E}_x \left( \int_0^{T_a^+} e^{-qt} dL_t \right) = \delta \overline{W}^{(q)}(a-b) \frac{r^{(q)}(x)}{r^{(q)}(a)} - \delta \overline{W}^{(q)}(x-b).$$

- Fix  $x \in \mathbb{R}$ . For  $q > 0$ , we have

$$\begin{aligned} \mathbb{E}_x \left( \int_0^\infty e^{-qt} dL_t \right) &= e^{-\varphi(q)b} \frac{r^{(q)}(x)}{\varphi(q)q \int_b^\infty e^{-\varphi(q)y} W^{(q)}(y) dy} \\ &\quad - \delta \overline{W}^{(q)}(x-b). \end{aligned}$$

For  $q = 0$ , it becomes infinity.

## Capital Injection

Assume  $\psi'(0+) > -\infty$  and  $q > 0$ . For any  $x \leq a$ , we have

$$\mathbb{E}_x \left( \int_{[0, T_a^+]} e^{-qt} dR_t \right) = \tilde{r}^{(q)}(a) \frac{r^{(q)}(x)}{r^{(q)}(a)} - \tilde{r}^{(q)}(x),$$

$$\begin{aligned} \mathbb{E}_x \left( \int_{[0, \infty)} e^{-qt} dR_t \right) &= -\tilde{r}^{(q)}(x) + \left( \int_b^\infty e^{-\varphi(q)(y-b)} Z^{(q)}(y) dy \right) \\ &\quad \times \frac{r^{(q)}(x)}{q \int_b^\infty e^{-\varphi(q)(y-b)} W^{(q)}(y) dy}, \end{aligned}$$

where

$$\tilde{r}^{(q)}(x) := \bar{Z}^{(q)}(x) + \frac{\psi'(0+)}{q} + \delta \int_b^x \mathbb{W}^{(q)}(x-y) Z^{(q)}(y) dy, \quad x \in \mathbb{R}.$$

## Occupation Time

For any  $p \geq 0$ ,  $q \geq -p$ ,  $a > 0$  and  $x \leq a$ ,

$$\mathbb{E}_x \left( e^{-pT_a^+ - q \int_0^{T_a^+} 1_{\{V_s < b\}} ds} \right) = \frac{\mathcal{R}^{(p,q)}(x)}{\mathcal{R}^{(p,q)}(a)},$$

$$\mathbb{E}_x \left( e^{-pT_a^+ - q \int_0^{T_a^+} 1_{\{V_s > b\}} ds} \right) = \frac{\mathcal{L}^{(p,q)}(x)}{\mathcal{L}^{(p,q)}(a)},$$

where

$$\begin{aligned} \mathcal{R}^{(p,q)}(x) &:= Z^{(p+q)}(x) - q\overline{W}^{(p)}(x-b) \\ &\quad - (p+q) \int_b^x \mathbb{W}^{(p)}(x-y) \left( q\overline{W}^{(p+q)}(y) - \delta W^{(p+q)}(y) \right) dy, \end{aligned}$$

$$\begin{aligned} \mathcal{L}^{(p,q)}(x) &= Z^{(p)}(x) + q\overline{W}^{(p+q)}(x-b) \\ &\quad + p \int_b^x \mathbb{W}^{(p+q)}(x-y) \left( q\overline{W}^{(p)}(y) + \delta W^{(p)}(y) \right) dy. \end{aligned}$$

# Optimization w/ singular&abs. cont. control

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- Joint work with B. Avanzi, B. Wong, and J.L. Pérez.
- $Y$  is a spectrally positive Lévy process.
- A dividend strategy  $\pi := (A_t^\pi, S_t^\pi; t \geq 0)$ 
  - $S^\pi$ : usual control (nondecreasing, right-continuous, and adapted)
  - $A^\pi$ : absolutely continuous control  $A_t^\pi = \int_0^t a_s^\pi ds$ ,  $t \geq 0$ , with  $a^\pi$  restricted to take values in  $[0, \delta]$  uniformly in time.
- The controlled risk process becomes

$$U_t^\pi := Y_t - A_t^\pi - S_t^\pi, \quad t \geq 0.$$

## Optimization w/ singular&abs. cont. control

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- We want to maximize

$$v_\pi(x) = \mathbb{E}_x \left( \int_0^{\sigma^\pi} e^{-qt} dA_t^\pi + \beta \int_{[0, \sigma^\pi]} e^{-qt} dS_t^\pi + \rho e^{-q\sigma^\pi} \right),$$

where

$$\sigma^\pi := \inf\{t > 0 : U_t^\pi < 0\},$$

is the time to ruin.

- To activate  $S^\pi$ , one needs to pay (proportional) costs:  $S^\pi$ :

$$0 < \beta < 1.$$

- $\rho \in \mathbb{R}$  is a terminal reward/penalty.
- Let  $\mathcal{A}$  be the set of all admissible strategies that satisfy the above conditions and

$$\Delta S_t^\pi \leq U_{t-}^\pi + \Delta Y_t, \quad t \geq 0.$$



## Two layer $(a, b)$ -strategy

- It is conjectured that it is optimal to
  - activate absolutely continuous control  $A$  when the process is above  $a$ .
  - activate singular control  $S$  when the process is above  $b > a$ .
- Under two-layer  $(a, b)$ -strategy, the controlled process becomes the refracted-reflected process – flipped case of the ones discussed.
- Let

$$v_{a,b}(x) = \mathbb{E}_x \left( \int_0^{\sigma_{a,b}} e^{-qt} dA_t^{a,b} + \beta \int_{[0, \sigma_{a,b})} e^{-qt} dS_t^{a,b} + \rho e^{-q\sigma_{a,b}} \right),$$

with its ruin time

$$\sigma_{a,b} := \sigma^{\pi_{a,b}} = \inf\{t > 0 : U_t^{a,b} := Y_t - A_t^{a,b} - S_t^{a,b} < 0\}.$$

## NPV under two layer $(a, b)$ -strategy

For all  $0 \leq a < b$  and  $x \geq 0$ , we have

$$v_{a,b}(x) = -\frac{\Gamma(a, b)}{q} \frac{r_{b-a}^{(q)}(b-x)}{r_{b-a}^{(q)}(b)} + \frac{\delta}{q} \mathbb{Z}^{(q)}(a-x) - \beta \tilde{r}_{b-a}^{(q)}(b-x),$$

where we define, for  $0 \leq a \leq b$ ,

$$\Gamma(a, b) := \delta \mathbb{Z}^{(q)}(a) - q\rho - q\beta \tilde{r}_{b-a}^{(q)}(b),$$

$$r_{b-a}^{(q)}(z) := Z^{(q)}(z) + q\delta \int_{b-a}^z \mathbb{W}^{(q)}(z-y) W^{(q)}(y) dy,$$

$$\tilde{r}_{b-a}^{(q)}(z) := \bar{Z}^{(q)}(z) + \frac{\psi'(0+)}{q} + \delta \int_{b-a}^z \mathbb{W}^{(q)}(z-y) Z^{(q)}(y) dy.$$

## Selection of $(a^*, b^*)$

1. If condition

$$C_b : \Gamma(a, b) = 0$$

holds, then  $v_{a,b}$  is continuously differentiable (resp. twice continuously differentiable) at  $b$  when  $Y$  has paths of bounded (resp. unbounded) variation.

2. Additionally if condition

$$C'_a : \gamma(a, b) := \beta^{-1} - Z^{(q)}(b - a) = 0$$

holds, then  $v_{a,b}$  is continuously differentiable (resp. twice continuously differentiable) at  $a$  when  $Y$  has paths of bounded (resp. unbounded) variation.

## Existence of $(a^*, b^*)$

- We have  $\frac{\partial}{\partial a}\Gamma(a, b) = \delta q \beta \mathbb{W}^{(q)}(a) \gamma(a, b)$ .
- If  $a \mapsto \Gamma(a, b^*)$  gets tangent to the  $x$ -axis at  $a^* > 0$ , then necessarily  $\Gamma(a^*, b^*) = \gamma(a^*, b^*) = 0$ .

There exist a pair  $(a^*, b^*)$  such that one of the following holds.

- (i)  $a^* = b^* = 0$  w/  $\Gamma(0) = \delta - q\rho - \beta\psi'_X(0+) \leq 0$ .
- (ii-1)  $a^* = 0 < b^*$  w/  $\Gamma(a^*, b^*) = 0$  and  $\beta^{-1} - Z^{(q)}(b^*) \geq 0$ , and  $\Gamma(0) > 0$ .
- (ii-2)  $0 < a^* < b^*$  w/  $\Gamma(a^*, b^*) = \gamma(a^*, b^*) = 0$ , and  $\Gamma(0) > 0$ .

## Form of $v_{a^*, b^*}$

- For  $b^* > 0$ ,

$$v_{a^*, b^*}(x) = \frac{\delta}{q} \mathbb{Z}^{(q)}(a^* - x) - \beta \tilde{r}_{b^* - a^*}^{(q)}(b^* - x), \quad x \geq 0,$$

where in particular

$$v_{a^*, b^*}(x) = \frac{\delta}{q} - \beta \left( \bar{\mathbb{Z}}^{(q)}(b^* - x) + \frac{\psi'(0+)}{q} \right), \quad a^* \leq x,$$

$$v_{a^*, b^*}(x) = \beta \left( x - b^* - \frac{\psi'_X(0+)}{q} \right) + \frac{\delta}{q}, \quad x \geq b^*.$$

- On the other hand, for  $a^* = b^* = 0$ ,

$$v_{0,0}(x) = \beta x + \rho, \quad x \geq 0.$$

- For both cases, it can be confirmed that

$$v_{a^*, b^*}(0) = \lim_{x \downarrow 0} v_{a^*, b^*}(x) = \rho.$$

## Verification lemma

Suppose  $\hat{\pi}$  is an admissible dividend strategy such that

1.  $v_{\hat{\pi}}$  is sufficiently smooth ( $C^1(0, \infty)$  [resp.  $C^2(0, \infty)$ ] when  $X$  has paths of bounded [resp. unbounded] variation) on  $(0, \infty)$ ,
2. it satisfies

$$\sup_{0 \leq r \leq \delta} ((\mathcal{L}_Y - q)v_{\hat{\pi}}(x) - rv'_{\hat{\pi}}(x) + r) \leq 0, \quad x > 0,$$
$$v'_{\hat{\pi}}(x) \geq \beta, \quad x > 0.$$

3.  $\rho = v_{\hat{\pi}}(0) \leq \lim_{x \downarrow 0} v_{\hat{\pi}}(x)$ .

Then  $v_{\hat{\pi}}(x) = v(x)$  for all  $x \geq 0$  and hence  $\hat{\pi}$  is an optimal strategy.

## Main results

### Lemma

The function  $v_{a^*, b^*}$  is concave and the following holds:

1. For  $x > a^*$ , we have  $\beta \leq v'_{a^*, b^*}(x) \leq 1$ ;
  2. For  $0 < x < a^*$ , we have  $v'_{a^*, b^*}(x) \geq 1 > \beta$ .
  3. Suppose  $a^* > 0$ . For  $0 < x < a^*$ , we have  $(\mathcal{L}_Y - q)v_{a^*, b^*}(x) = 0$ .
  4. Suppose  $b^* > 0$ . For  $a^* < x < b^*$ , we have  $(\mathcal{L}_X - q)v_{a^*, b^*}(x) + \delta = 0$ .
- (iii) For  $x > b^*$ ,  $(\mathcal{L}_X - q)v_{a^*, b^*}(x) + \delta \leq 0$ .

### Theorem

The two-layer  $(a^*, b^*)$  strategy for  $(a^*, b^*)$  is optimal, and the value function is given by  $v(x) = v_{a^*, b^*}(x)$  for all  $0 \leq x < \infty$ .

## Numerical results

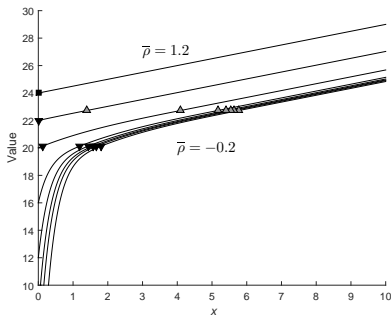
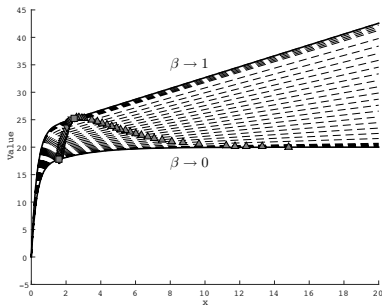


Figure: Sensitivity of the value function  $v(x)$  with respect to  $\bar{\rho} := q\rho/\delta$ .

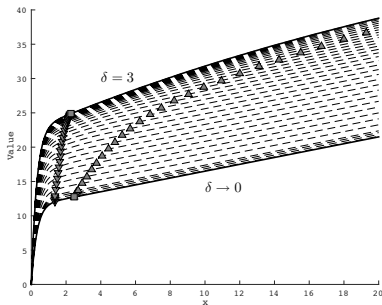


## Numerical results



**Figure:** Sensitivity of the value function  $v(x)$  with respect to  $\beta = [0.01, 0.02, 0.03, 0.04, 0.05, 0.1, \dots, 0.90, 0.95, 0.96, 0.97, 0.98, 0.99]$ .

## Numerical results



**Figure:** Sensitivity of the value function  $v(x)$  with respect to  $\delta = [0.01, 0.04, 0.07, 0.1, 0.2, \dots, 2.9, 3]$ .

## References

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